



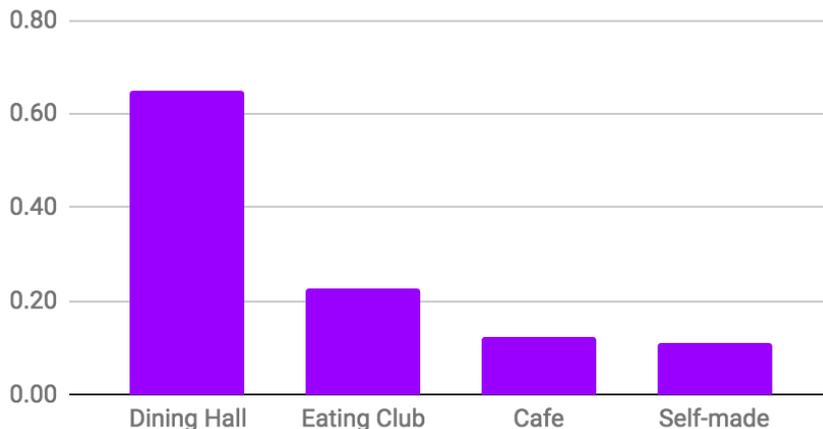
# Properties of Joint Distributions

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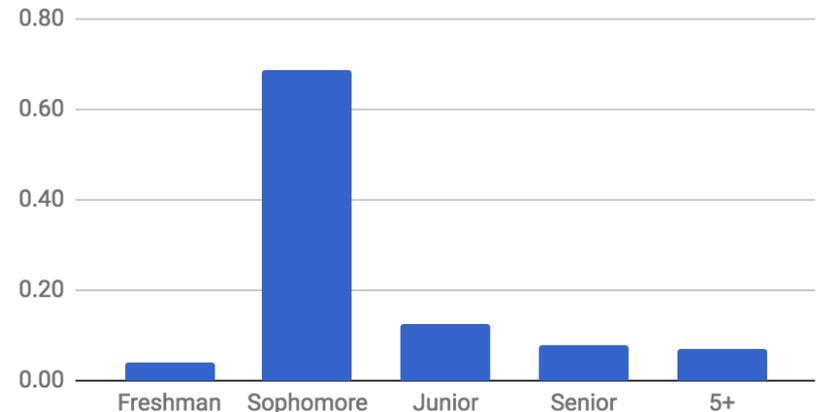
# Joint Probability Table

Joint Probability Table					
	Dining Hall	Eating Club	Cafe	Self-made	<b>Marginal Year</b>
Freshman	0.02	0.00	0.02	0.00	0.04
Sophomore	0.51	0.15	0.03	0.03	0.69
Junior	0.08	0.02	0.02	0.02	0.13
Senior	0.02	0.05	0.01	0.01	0.08
5+	0.02	0.01	0.05	0.05	0.07
<b>Marginal Status</b>	0.65	0.23	0.13	0.11	

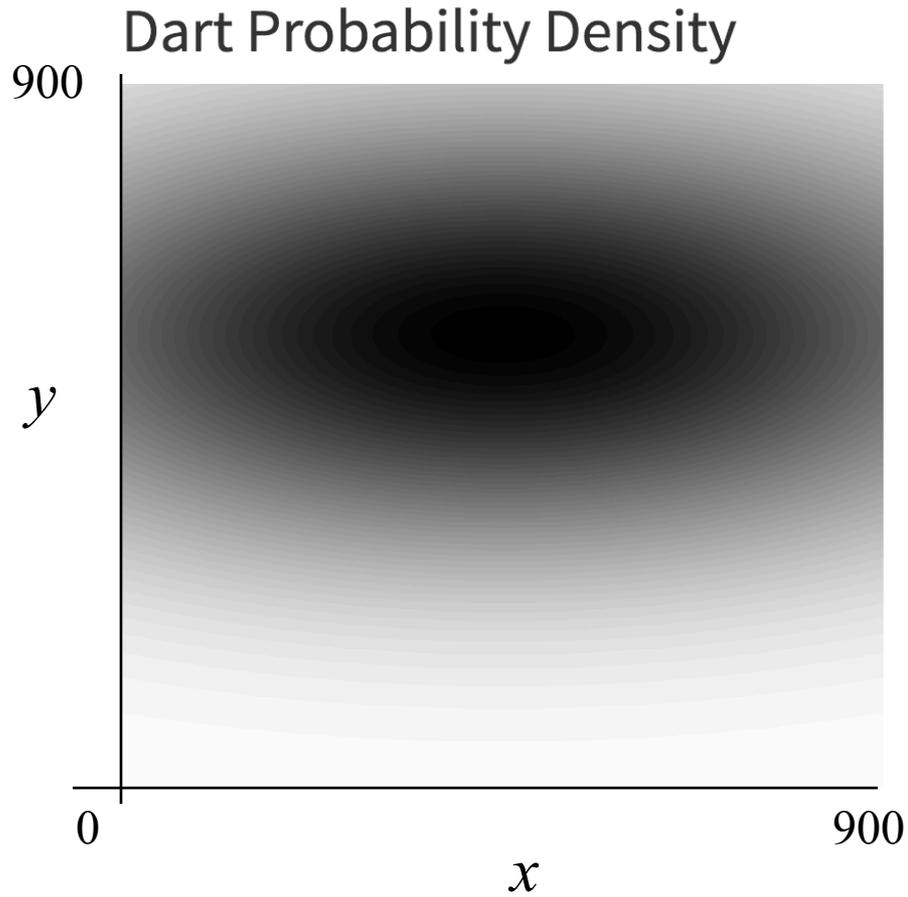
Marginal Lunch Probability



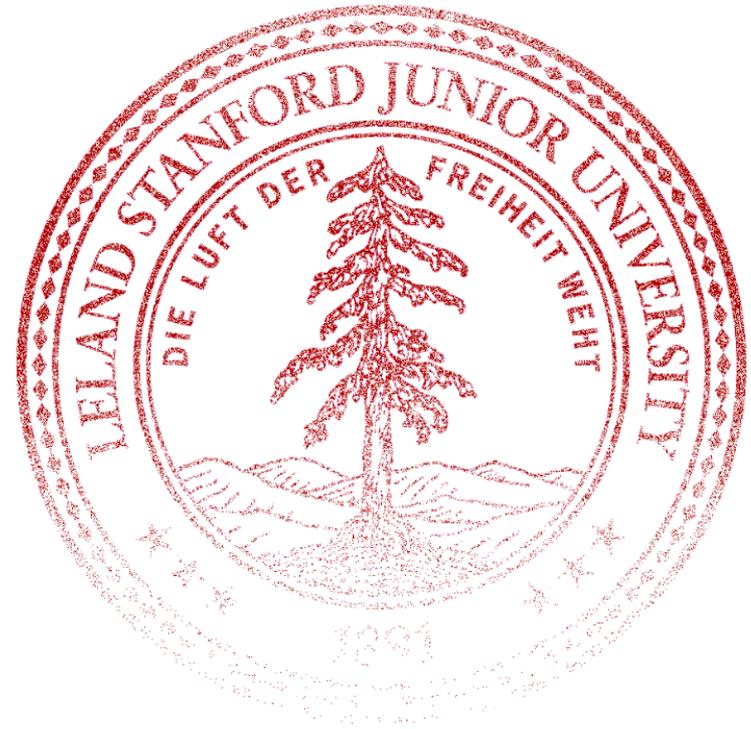
Marginal Year



# Continuous Joint Random Variables



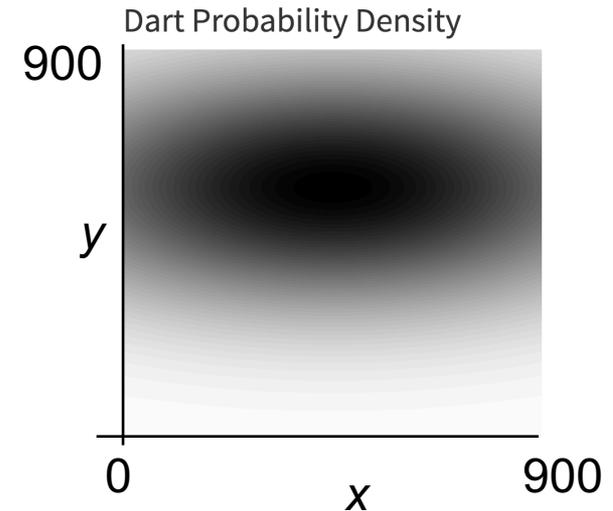
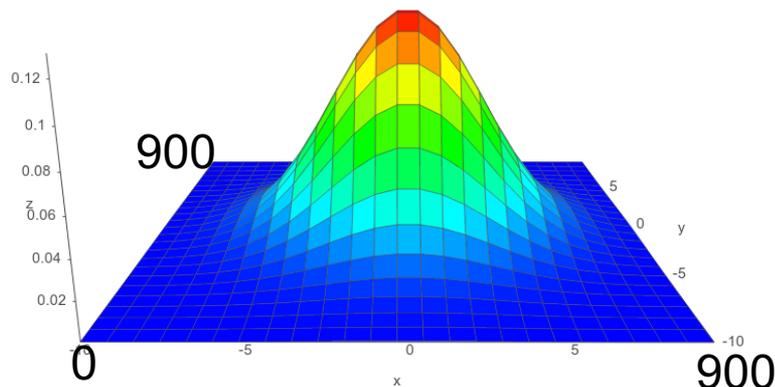
Dart Results



# Joint Probability Density Function



A **joint probability density function** gives the relative likelihood of **more than one** continuous random variable **each** taking on a specific value.



$$P(a_1 < X \leq a_2, b_1 < Y \leq b_2) = \int_{a_1}^{a_2} \int_{b_1}^{b_2} f_{X,Y}(x, y) dy dx$$

# Jointly Continuous

$$P(a_1 < X \leq a_2, b_1 < Y \leq b_2) = \int_{a_1}^{a_2} \int_{b_1}^{b_2} f_{X,Y}(x, y) dy dx$$

- Cumulative Density Function (CDF):

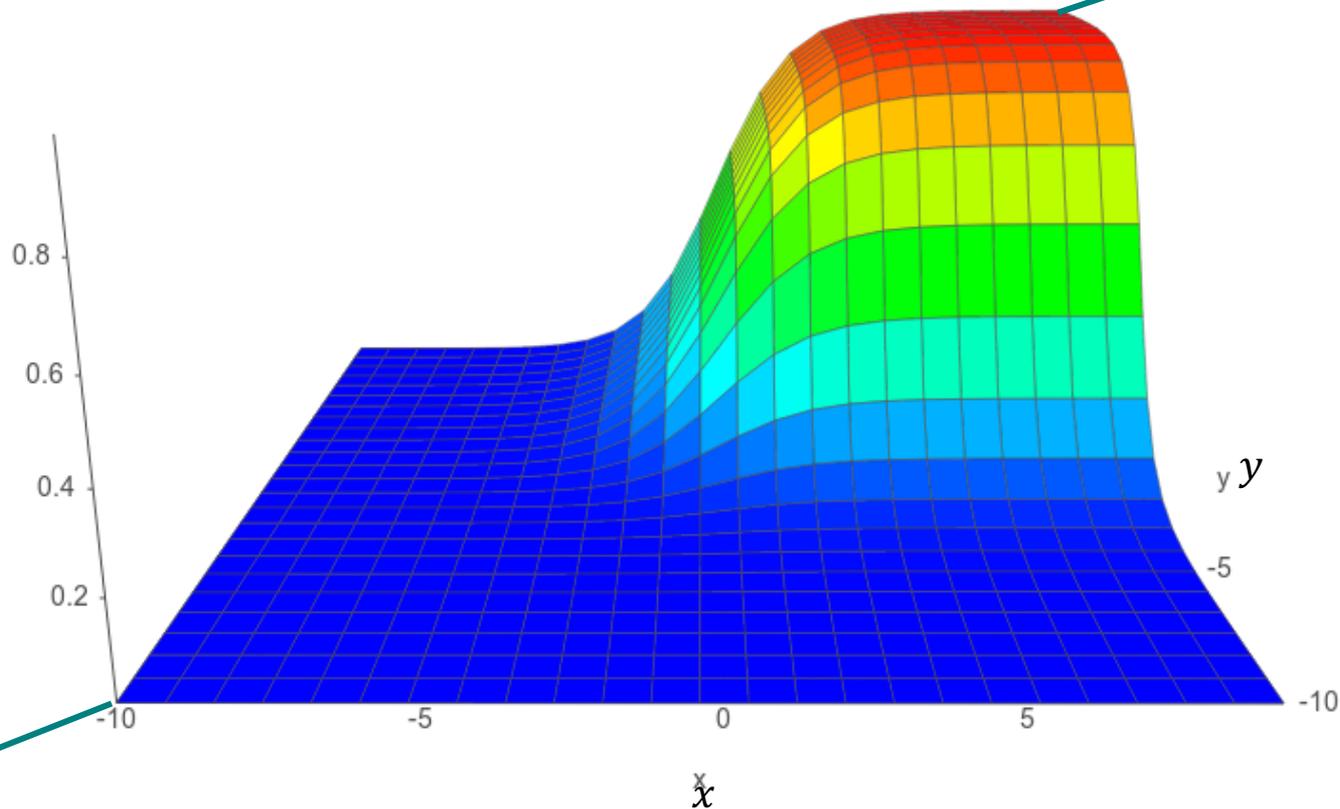
$$F_{X,Y}(a, b) = \int_{-\infty}^a \int_{-\infty}^b f_{X,Y}(x, y) dy dx$$

$$f_{X,Y}(a, b) = \frac{\partial^2}{\partial a \partial b} F_{X,Y}(a, b)$$

# Jointly CDF

$$F_{X,Y}(x,y) = P(X \leq x, Y \leq y)$$

to 1 as  
 $x \rightarrow +\infty,$   
 $y \rightarrow +\infty$



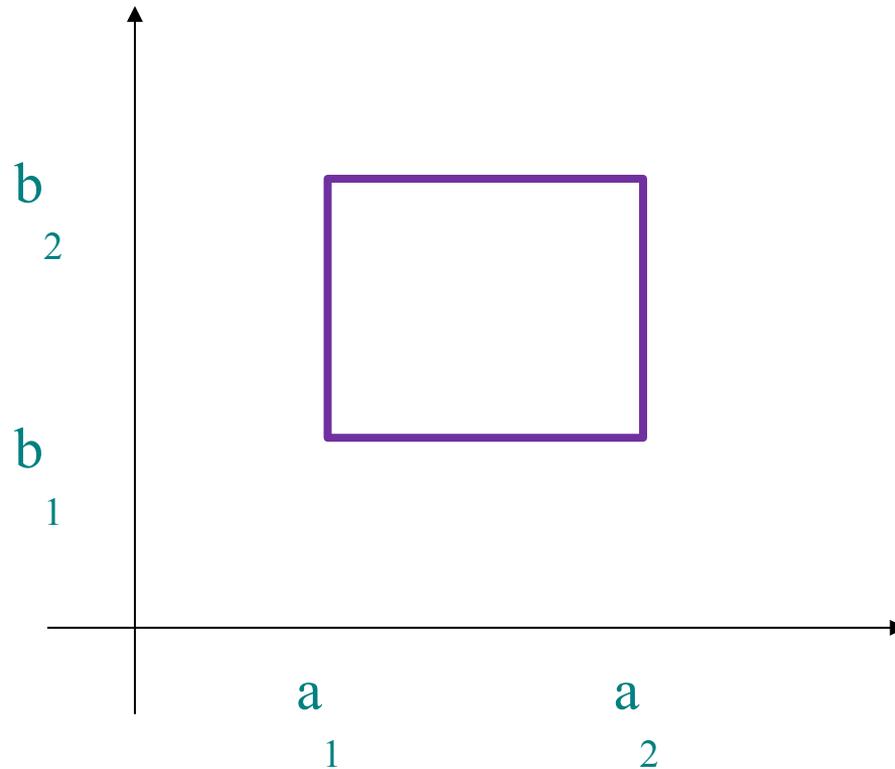
to 0 as

$x \rightarrow -\infty,$

$y \rightarrow -\infty$

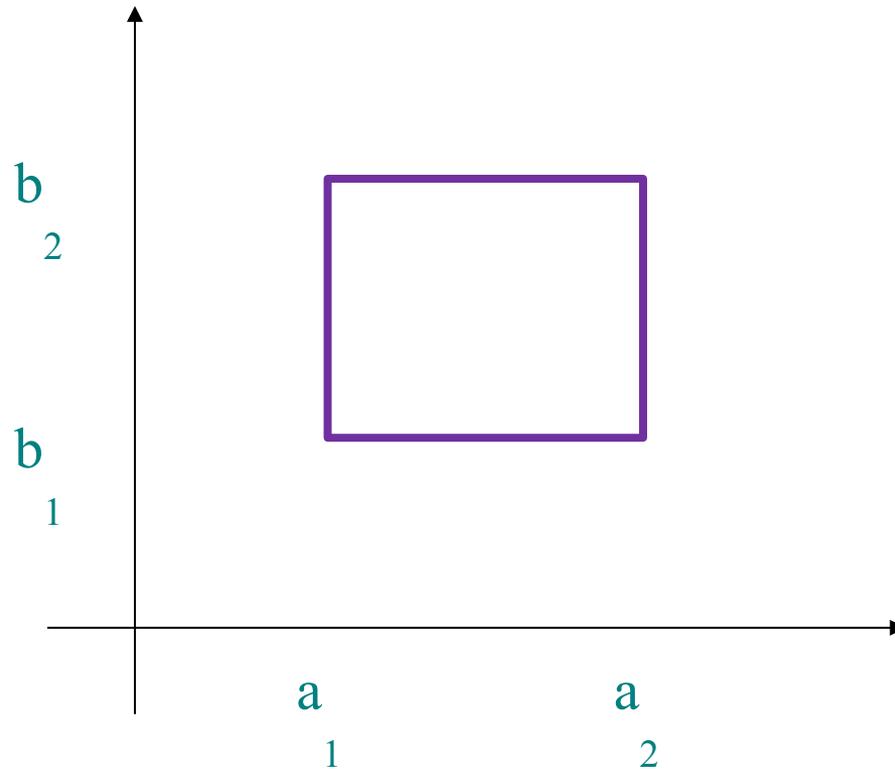
# Probabilities from Joint CDF

$$P(a_1 < X \leq a_2, b_1 < Y \leq b_2)$$



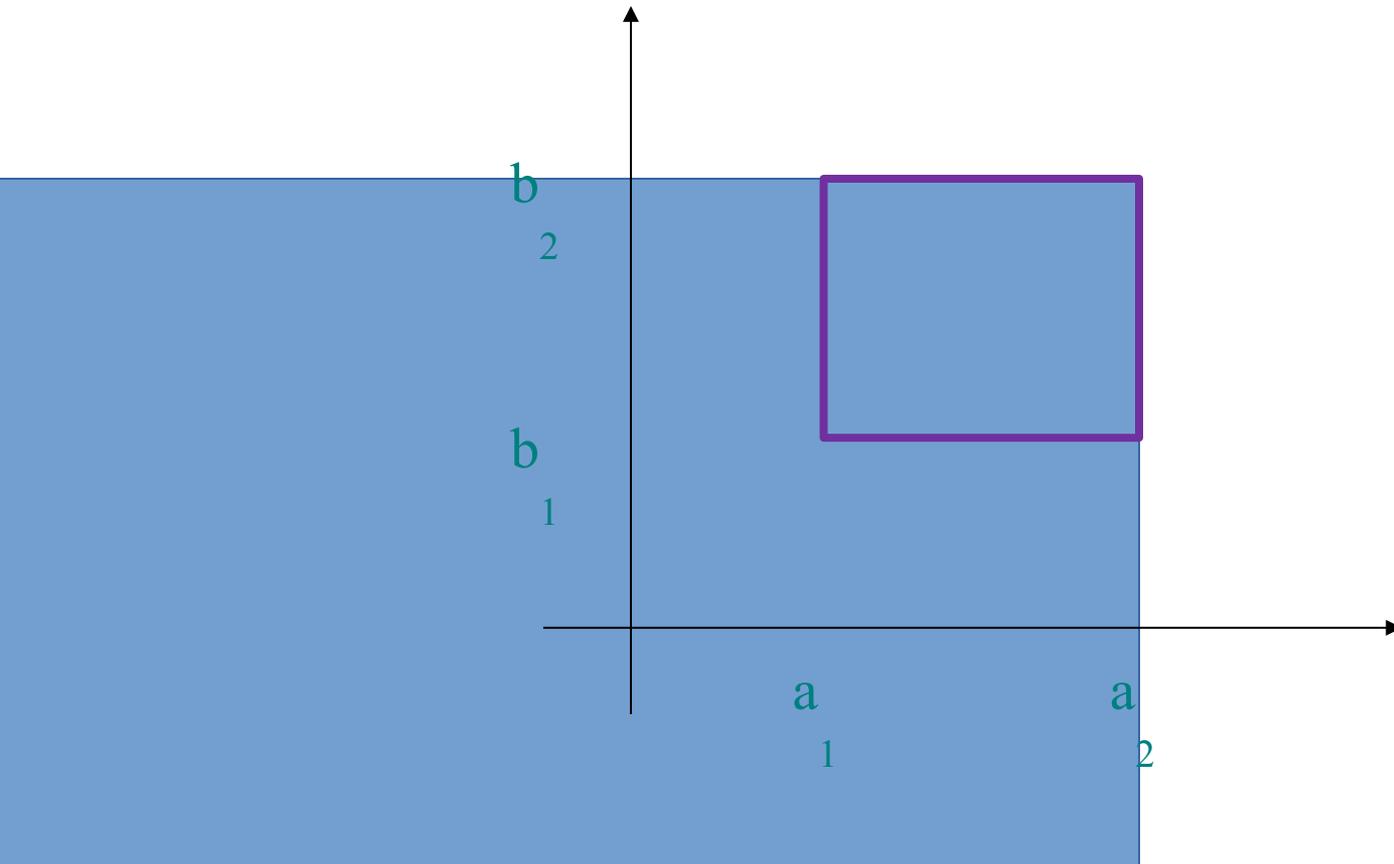
# Probabilities from Joint CDF

$$P(a_1 < X \leq a_2, b_1 < Y \leq b_2) = F_{X,Y}(a_2, b_2)$$



# Probabilities from Joint CDF

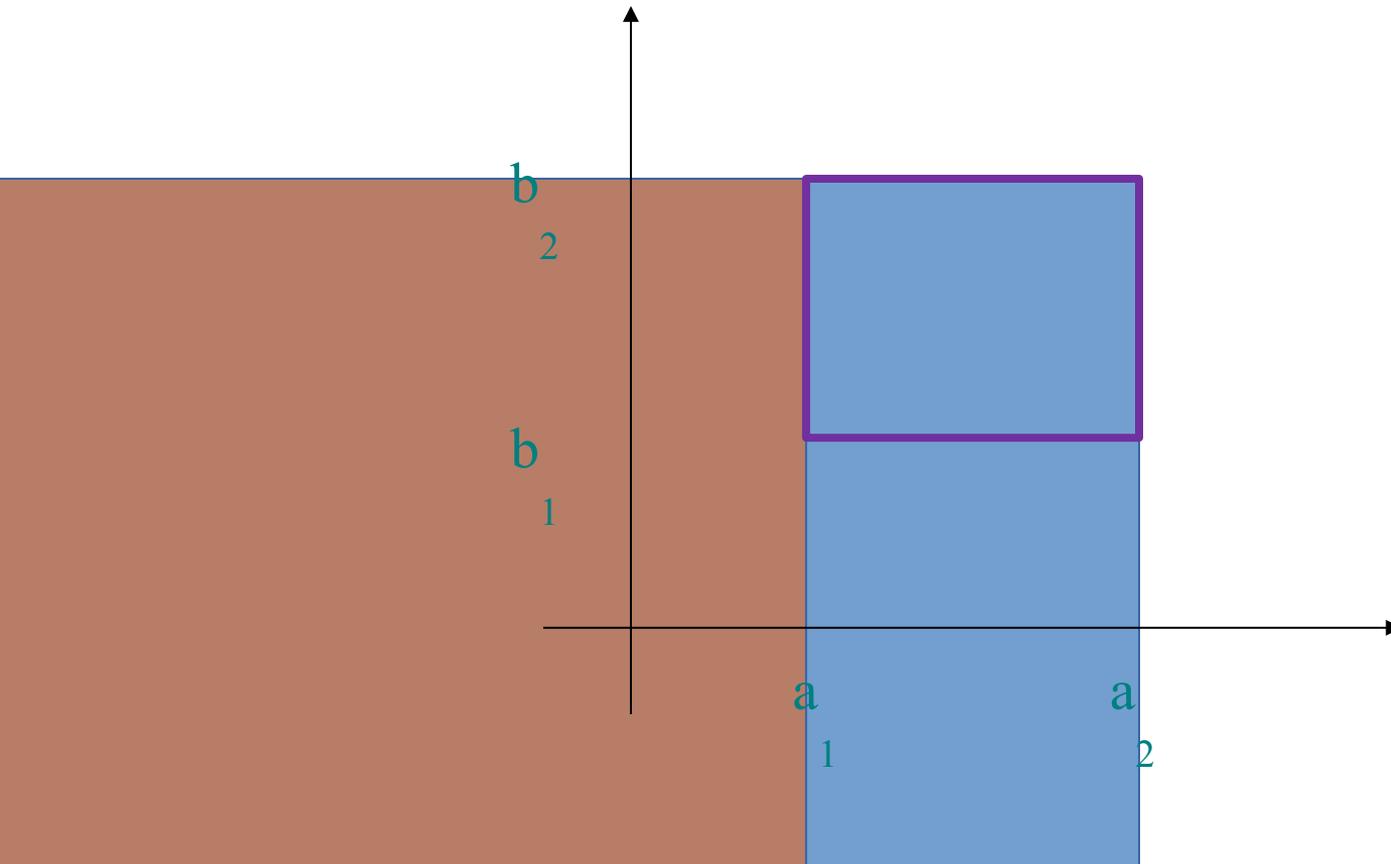
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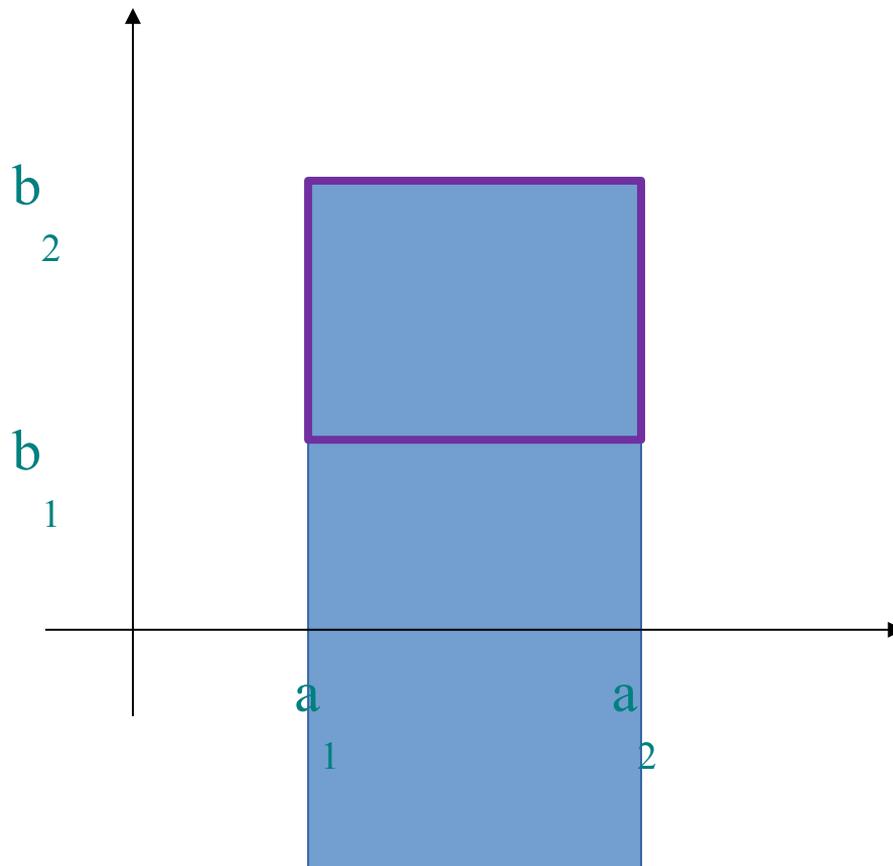
$$-F_{X,Y}(a_1, b_2)$$



# Probabilities from Joint CDF

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$$-F_{X,Y}(a_1, b_2)$$

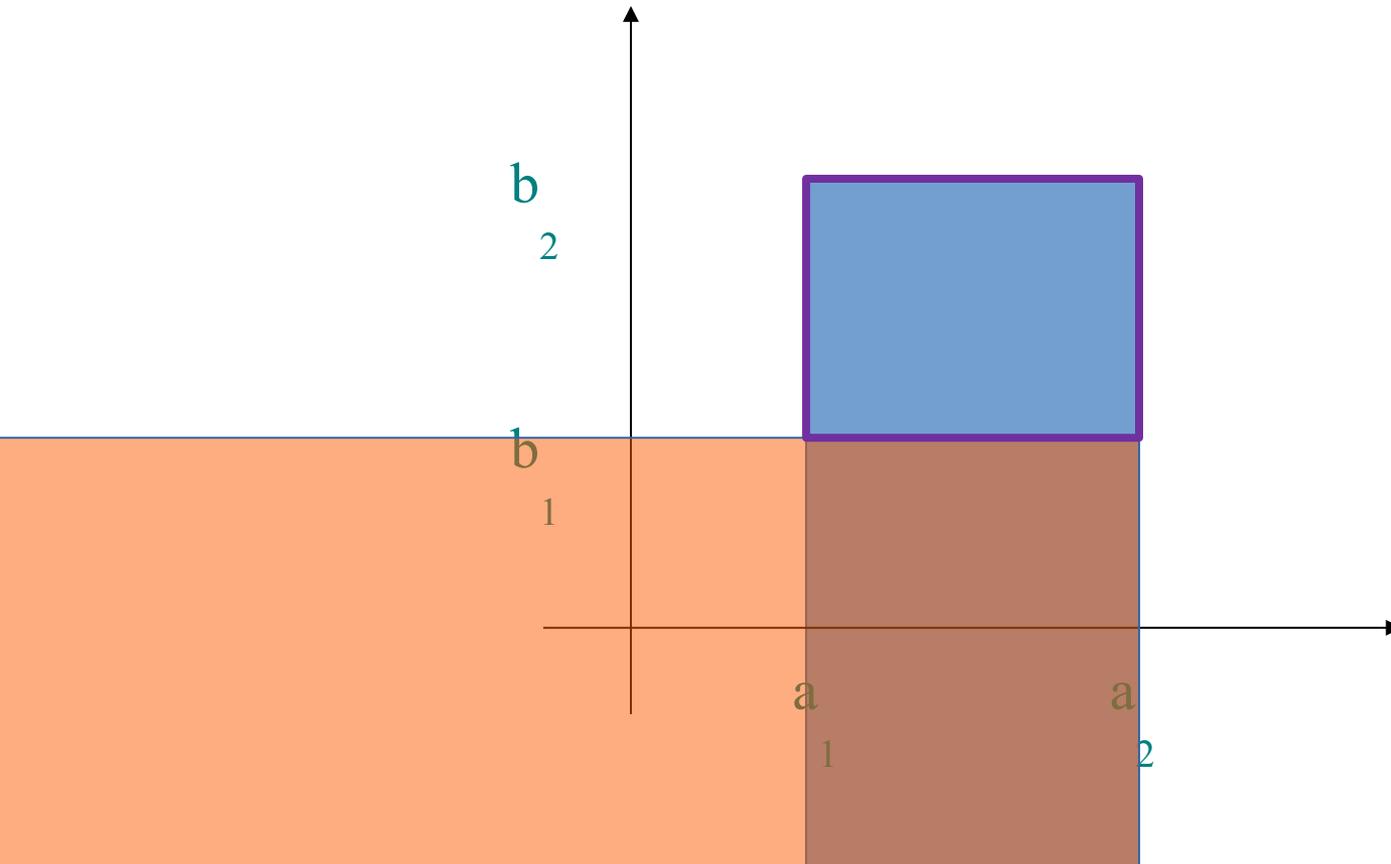


# Probabilities from Joint CDF

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$$-F_{X,Y}(a_1, b_2)$$

$$-F_{X,Y}(a_2, b_1)$$

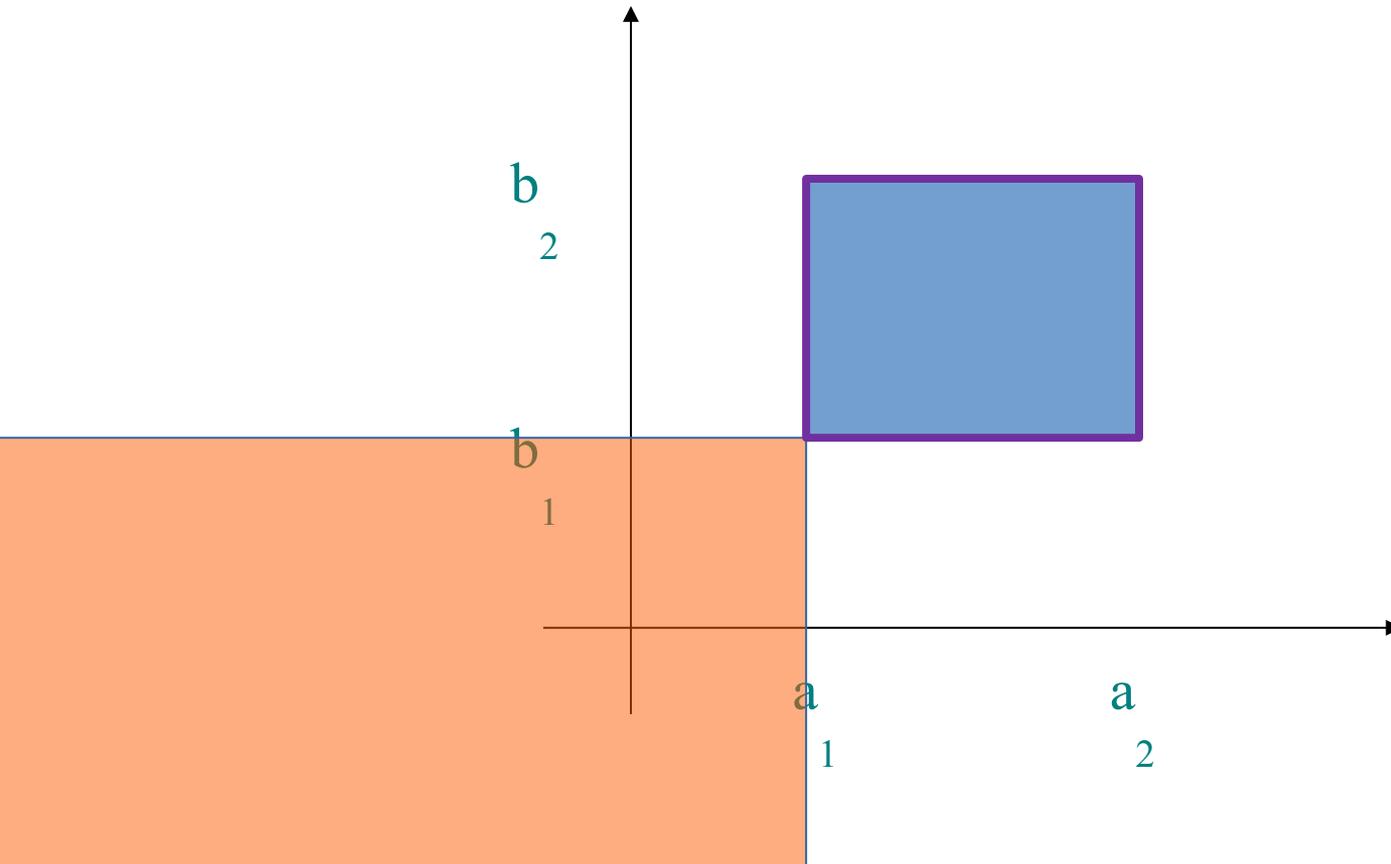


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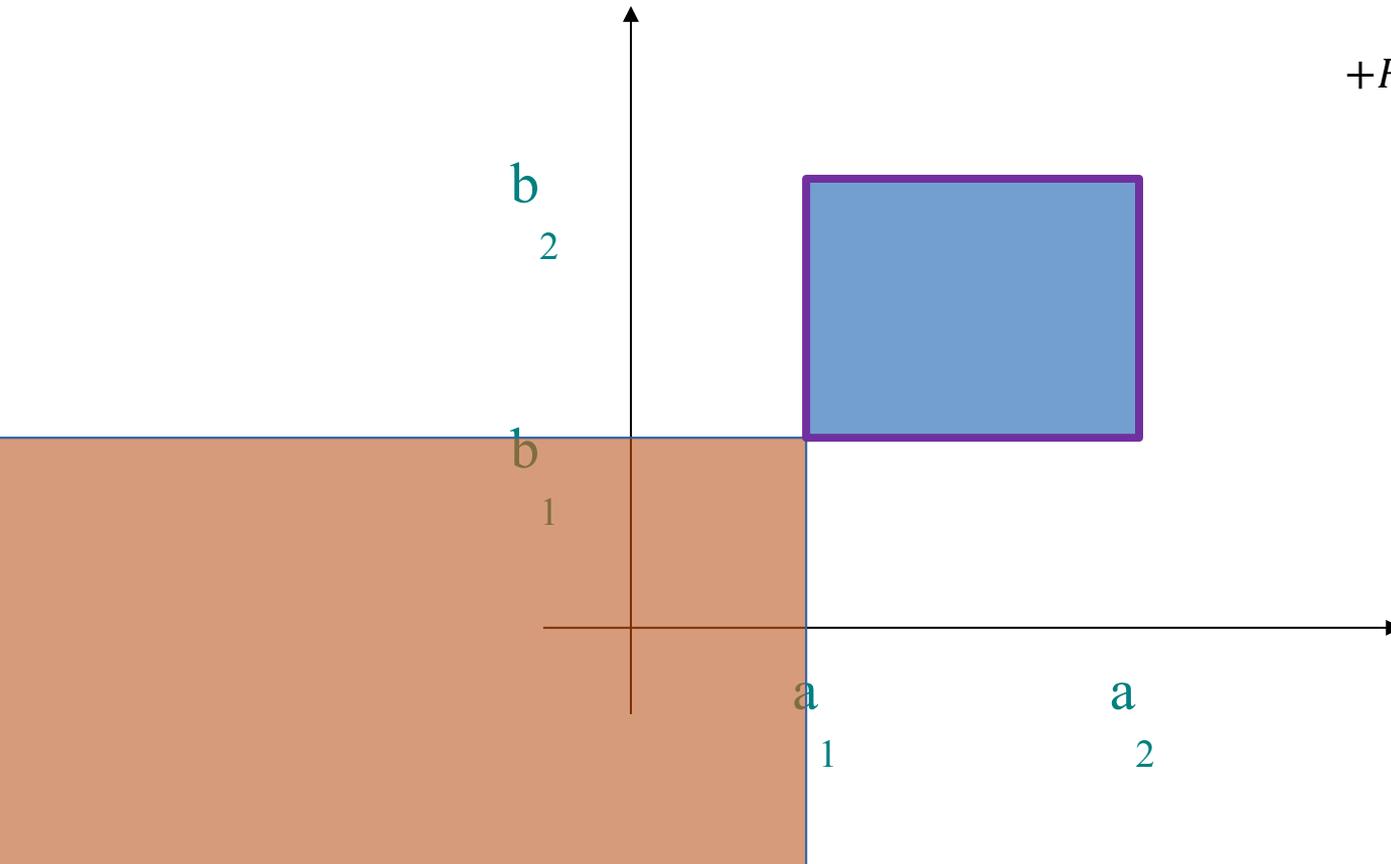
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$$-F_{X,Y}(a_2, b_1)$$

$$+F_{X,Y}(a_1, b_1)$$



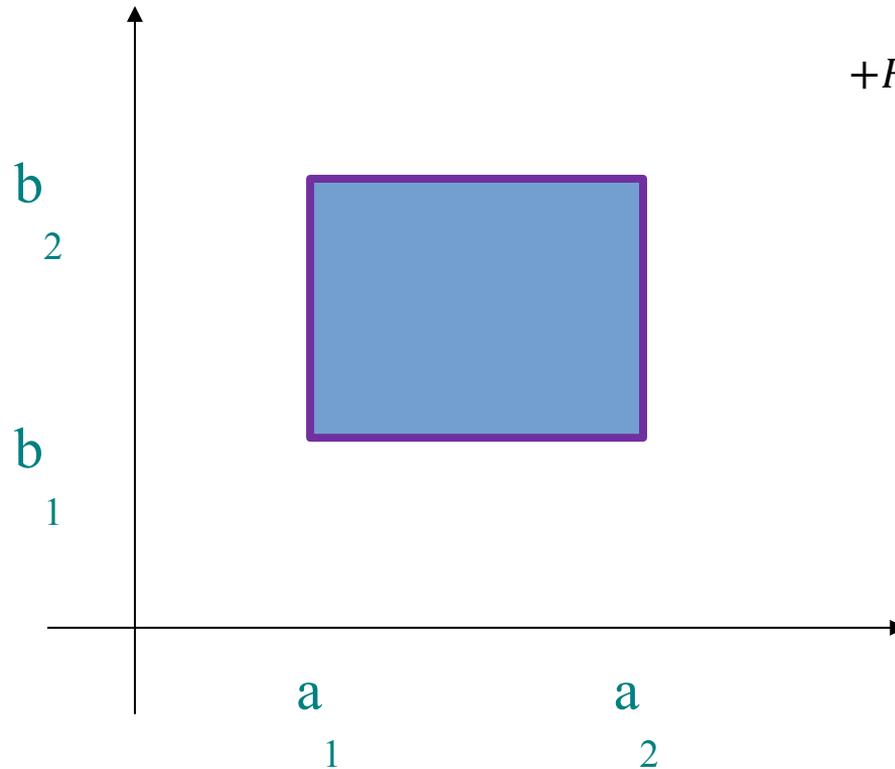
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$$-F_{X,Y}(a_1, b_2)$$

$$-F_{X,Y}(a_2, b_1)$$

$$+F_{X,Y}(a_1, b_1)$$



# Probability for Instagram!

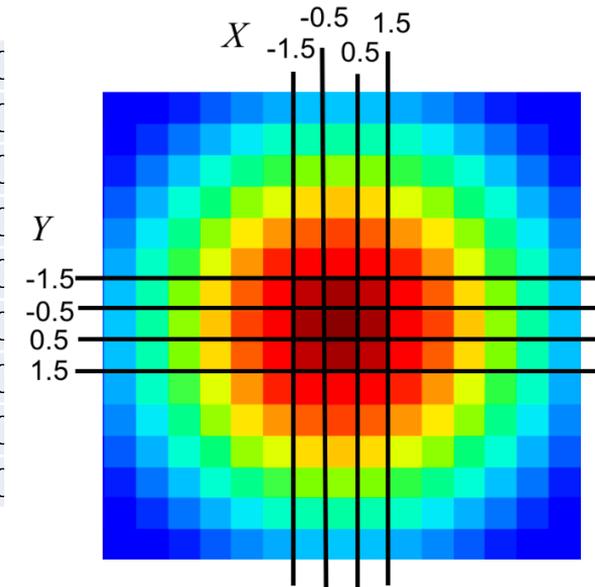


# Gaussian Blur

In image processing, a Gaussian blur is the result of blurring an image by a Gaussian function. It is a widely used effect in graphics software, typically to reduce image noise.



0.0000	0.0000	0.0000	0.0001	0.0001	0.0000
0.0000	0.0001	0.0005	0.0020	0.0032	0.0000
0.0000	0.0005	0.0052	0.0206	0.0326	0.0000
0.0001	0.0020	0.0206	0.0821	0.1300	0.0000
0.0001	0.0032	0.0326	0.1300	<b>0.2060</b>	0.0000
0.0001	0.0020	0.0206	0.0821	0.1300	0.0000
0.0000	0.0005	0.0052	0.0206	0.0326	0.0000
0.0000	0.0001	0.0005	0.0020	0.0032	0.0000
0.0000	0.0000	0.0000	0.0001	0.0001	0.0000



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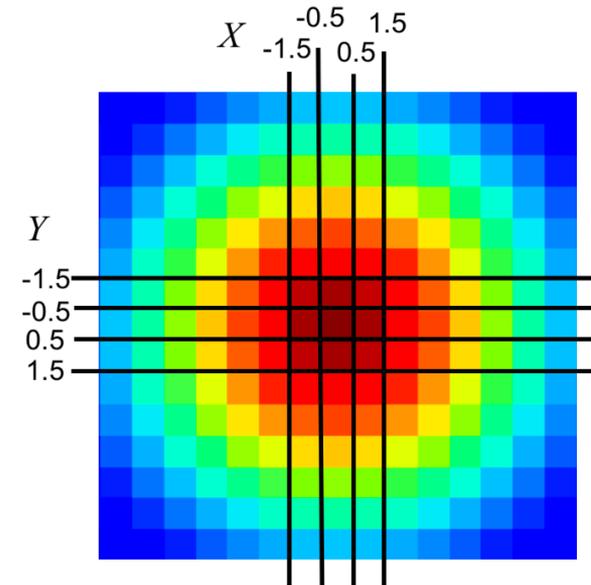
Gaussian blurring with  $\text{StDev} = 3$ , is based on a joint probability distribution:

**Joint PDF**

$$f_{X,Y}(x, y) = \frac{1}{2\pi \cdot 3^2} e^{-\frac{x^2+y^2}{2 \cdot 3^2}}$$

**Joint CDF**

$$F_{X,Y}(x, y) = \Phi\left(\frac{x}{3}\right) \cdot \Phi\left(\frac{y}{3}\right)$$



Used to generate this weight matrix



# Gaussian Blur

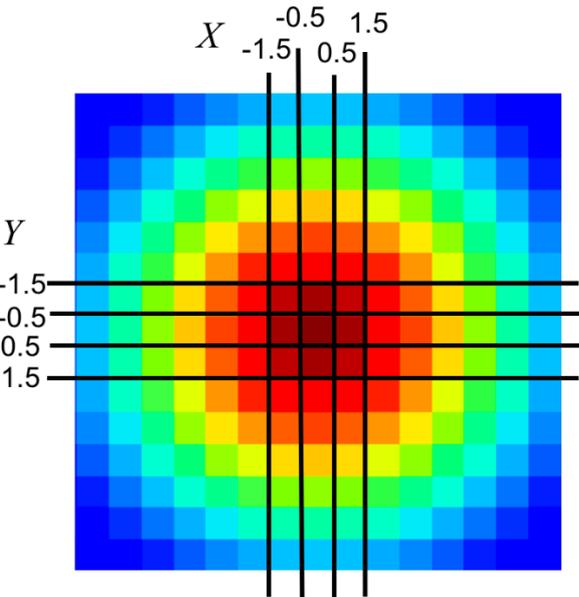
## Joint PDF

$$f_{X,Y}(x,y) = \frac{1}{2\pi \cdot 3^2} e^{-\frac{x^2+y^2}{2 \cdot 3^2}}$$

## Joint CDF

$$F_{X,Y}(x,y) = \Phi\left(\frac{x}{3}\right) \cdot \Phi\left(\frac{y}{3}\right)$$

## Weight Matrix



Each pixel is given a weight equal to the probability that  $X$  and  $Y$  are both within the pixel bounds. The center pixel covers the area where

$$-0.5 \leq x \leq 0.5 \text{ and } -0.5 \leq y \leq 0.5$$

What is the weight of the center pixel?

---

$$\begin{aligned} &P(-0.5 < X < 0.5, -0.5 < Y < 0.5) \\ &= P(X < 0.5, Y < 0.5) - P(X < 0.5, Y < -0.5) \\ &\quad - P(X < -0.5, Y < 0.5) + P(X < -0.5, Y < -0.5) \\ &= \phi\left(\frac{0.5}{3}\right) \cdot \phi\left(\frac{0.5}{3}\right) - 2\phi\left(\frac{0.5}{3}\right) \cdot \phi\left(\frac{-0.5}{3}\right) \\ &\quad + \phi\left(\frac{-0.5}{3}\right) \cdot \phi\left(\frac{-0.5}{3}\right) \\ &= 0.5662^2 - 2 \cdot 0.5662 \cdot 0.4338 + 0.4338^2 = 0.206 \end{aligned}$$

# Properties of Joint Distributions

# Boolean Operation on Variable = Event

Recall: any boolean question about a random variable makes for an event. For example:



$$P(X \leq 5)$$

$$P(Y = 6)$$

$$P(5 \leq Z \leq 10)$$

# Independence and Random Variables

# Independent Discrete Variables

- Two discrete random variables  $X$  and  $Y$  are called **independent** if:

$$p(x, y) = p_X(x)p_Y(y) \quad \text{for all } x, y$$

$$P(X = x, Y = y) = P(X = x) \cdot P(Y = y)$$

- Intuitively: knowing the value of  $X$  tells us nothing about the distribution of  $Y$  (and vice versa)
  - If two variables are **not** independent, they are called **dependent**
- Similar conceptually to independent *events*, but we are dealing with multiple **variables**
  - Keep your events and variables distinct (and clear)!

# Is Year Independent of Lunch?

Joint Probability Table					
	Dining Hall	Eating Club	Cafe	Self-made	Marginal Year
Freshman	0.03	0.00	0.02	0.00	0.05
Sophomore	0.50	0.15	0.03	0.03	0.68
Junior	0.08	0.02	0.02	0.02	0.12
Senior	0.02	0.05	0.01	0.01	0.08
5+	0.02	0.01	0.05	0.05	0.07
Marginal Status	0.65	0.22	0.12	0.11	

For all values of Year, Status:

$$P(\text{Year} = y, \text{Lunch} = s) = P(\text{Year} = y)P(\text{Lunch} = s)$$

0.50                      0.68                      0.65

Yes!

# Is Year Independent of Lunch?

Joint Probability Table					
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Marginal Status	0.65	0.22	0.12	0.11	

For all values of Year, Status:

$$P(\text{Year} = y, \text{Lunch} = s) = P(\text{Year} = y)P(\text{Lunch} = s)$$

0.03

0.68

0.12

0.08

No ☹️

# Aside: Butterfly Effect



# Coin Flips

- Flip coin with probability  $p$  of “heads”
  - Flip coin a total of  $n + m$  times
  - Let  $X$  = number of heads in first  $n$  flips
  - Let  $Y$  = number of heads in next  $m$  flips

$$P(X = x, Y = y) = \binom{n}{x} p^x (1-p)^{n-x} \binom{m}{y} p^y (1-p)^{m-y}$$
$$= P(X = x)P(Y = y)$$

- $X$  and  $Y$  are independent
- Let  $Z$  = number of total heads in  $n + m$  flips
- Are  $X$  and  $Z$  independent?
  - What if you are told  $Z = 0$ ?

# Recall: Poisson Random Variable

- $X$  is a **Poisson** Random Variable: the number of occurrences in a fixed interval of time.

$$X \sim \text{Poi}(\lambda)$$

- $\lambda$  is the “rate”
- $X$  takes on values 0, 1, 2...
- has distribution (PMF):

$$P(X = k) = e^{-\lambda} \frac{\lambda^k}{k!}$$

# Web Server Requests

- Let  $N = \#$  of requests to web server/day
  - Suppose  $N \sim \text{Poi}(\lambda)$
  - Each request comes from a human (probability =  $p$ ) or from a “bot” (probability =  $(1 - p)$ ), independently
  - $X = \#$  requests from humans/day  $(X | N) \sim \text{Bin}(N, p)$
  - $Y = \#$  requests from bots/day  $(Y | N) \sim \text{Bin}(N, 1 - p)$

$$P(X = i, Y = j) = \frac{P(X = i, Y = j | X + Y = i + j)P(X + Y = i + j)}{P(X = i, Y = j | X + Y = i + j)P(X + Y = i + j) + P(X = i, Y = j | X + Y \neq i + j)P(X + Y \neq i + j)}$$

Probability of  $i$  human requests and  $j$  bot requests

Probability of  $i$  human requests and  $j$  bot requests | we got  $i + j$  requests

Probability of number of requests in a day was  $i + j$

# Web Server Requests

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$$P(X = i, Y = j) = P(X = i, Y = j | X + Y = i + j)P(X + Y = i + j) + P(X = i, Y = j | X + Y \neq i + j)P(X + Y \neq i + j)$$

- Note:  $P(X = i, Y = j | X + Y \neq i + j) = 0$

You got  $i$  human requests  
and  $j$  bot requests

You did not get  $i + j$   
requests

# Web Server Requests

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$$P(X = i, Y = j) = P(X = i, Y = j | X + Y = i + j)P(X + Y = i + j)$$

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$$P(X = i, Y = j) = P(X = i, Y = j | X + Y = i + j)P(X + Y = i + j)$$

$$P(X = i, Y = j | X + Y = i + j) = \binom{i+j}{i} p^i (1-p)^j$$

$$P(X + Y = i + j) = e^{-\lambda} \frac{\lambda^{i+j}}{(i+j)!}$$

$$P(X = i, Y = j) = \binom{i+j}{i} p^i (1-p)^j e^{-\lambda} \frac{\lambda^{i+j}}{(i+j)!}$$

Binomial

Poisson

Joint

# Web Server Requests

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$$P(X = i, Y = j) = \frac{(i+j)!}{i!j!} p^i (1-p)^j e^{-\lambda} \frac{\lambda^{i+j}}{(i+j)!} = e^{-\lambda} \frac{(\lambda p)^i}{i!} \cdot \frac{(\lambda(1-p))^j}{j!}$$

Reorder  
terms

$$= e^{-\lambda p} \frac{(\lambda p)^i}{i!} \cdot e^{-\lambda(1-p)} \frac{(\lambda(1-p))^j}{j!} = P(X = i)P(Y = j)$$

- Where  $X \sim \text{Poi}(\lambda p)$  and  $Y \sim \text{Poi}(\lambda(1 - p))$
- $X$  and  $Y$  are independent!

# Independent Continuous Variables

- Two continuous random variables  $X$  and  $Y$  are called **independent** if:

$$P(X \leq a, Y \leq b) = P(X \leq a) P(Y \leq b) \text{ for any } a, b$$

- Equivalently:

$$F_{X,Y}(a, b) = F_X(a)F_Y(b) \text{ for all } a, b$$

$$f_{X,Y}(a, b) = f_X(a)f_Y(b) \text{ for all } a, b$$

- More generally, joint density factors separately:

$$f_{X,Y}(x, y) = h(x)g(y) \text{ where } -\infty < x, y < \infty$$

# Is the Blur Distribution Independent?

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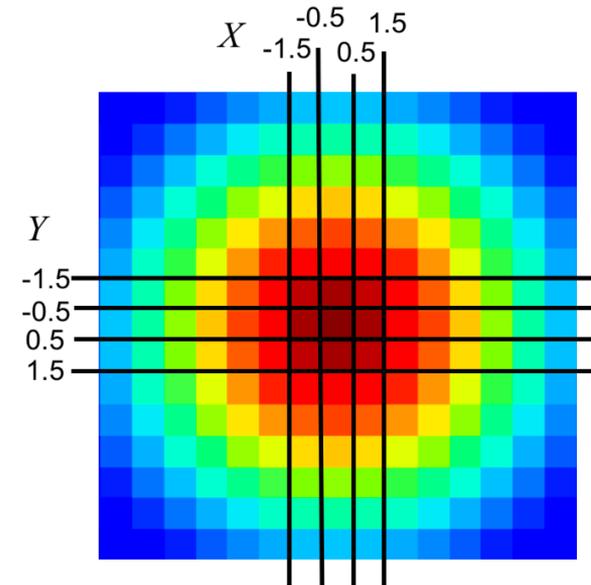
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**Joint CDF**

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Used to generate this weight matrix



# Pop Quiz (just kidding)

- Consider joint density function of X and Y:

$$f_{X,Y}(x, y) = 6e^{-3x}e^{-2y} \quad \text{for } 0 < x, y < \infty$$

- Are X and Y independent? **Yes!**

Let  $h(x) = 3e^{-3x}$  and  $g(y) = 2e^{-2y}$ , so  $f_{X,Y}(x, y) = h(x)g(y)$

- Consider joint density function of X and Y:

$$f_{X,Y}(x, y) = 4xy \quad \text{for } 0 < x, y < 1$$

- Are X and Y independent? **Yes!**

Let  $h(x) = 2x$  and  $g(y) = 2y$ , so  $f_{X,Y}(x, y) = h(x)g(y)$

- Now add constraint that:  $0 < (x + y) < 1$

- Are X and Y independent? **No!**

- Cannot capture constraint on  $x + y$  in factorization!

# Independence of Multiple Variables

- $n$  random variables  $X_1, X_2, \dots, X_n$  are called **independent** if:

$$P(X_1 = x_1, X_2 = x_2, \dots, X_n = x_n) = \prod_{i=1}^n P(X_i = x_i) \quad \text{for all subsets of } x_1, x_2, \dots, x_n$$

- Analogously, for continuous random variables:

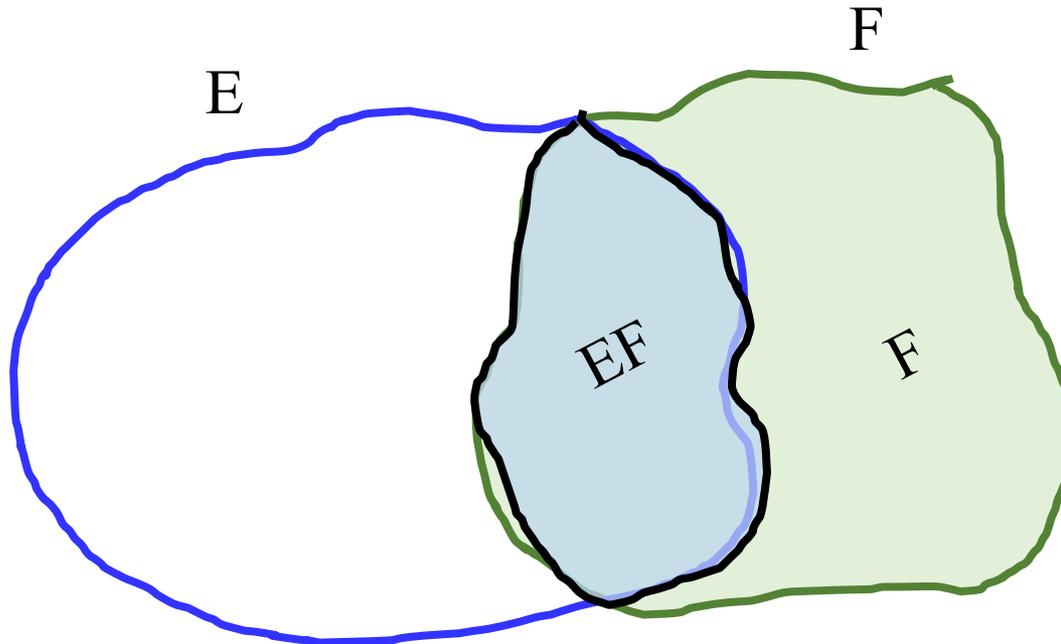
$$P(X_1 \leq a_1, X_2 \leq a_2, \dots, X_n \leq a_n) = \prod_{i=1}^n P(X_i \leq a_i) \quad \text{for all subsets of } a_1, a_2, \dots, a_n$$

# Conditionals with multiple variables

# Discrete Conditional Distribution

- Recall that for events  $E$  and  $F$ :

$$P(E | F) = \frac{P(EF)}{P(F)} \quad \text{where } P(F) > 0$$



# Discrete Conditional Distributions

- Recall that for events E and F:

$$P(E | F) = \frac{P(EF)}{P(F)} \quad \text{where } P(F) > 0$$

- Now, have X and Y as discrete random variables
  - Conditional PMF of X given Y (where  $p_Y(y) > 0$ ):

$$P_{X|Y}(x | y) = P(X = x | Y = y) = \frac{P(X = x, Y = y)}{P(Y = y)} = \frac{p_{X,Y}(x, y)}{p_Y(y)}$$

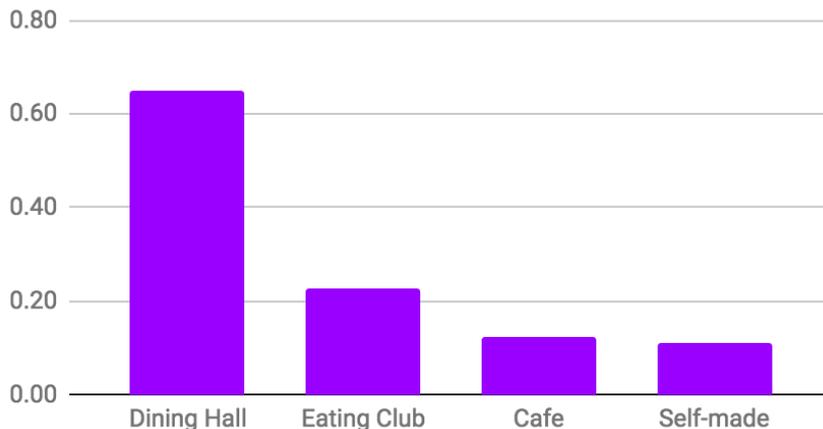
- Conditional CDF of X given Y (where  $p_Y(y) > 0$ ):

$$\begin{aligned} F_{X|Y}(a | y) &= P(X \leq a | Y = y) = \frac{P(X \leq a, Y = y)}{P(Y = y)} \\ &= \frac{\sum_{x \leq a} p_{X,Y}(x, y)}{p_Y(y)} = \sum_{x \leq a} p_{X|Y}(x | y) \end{aligned}$$

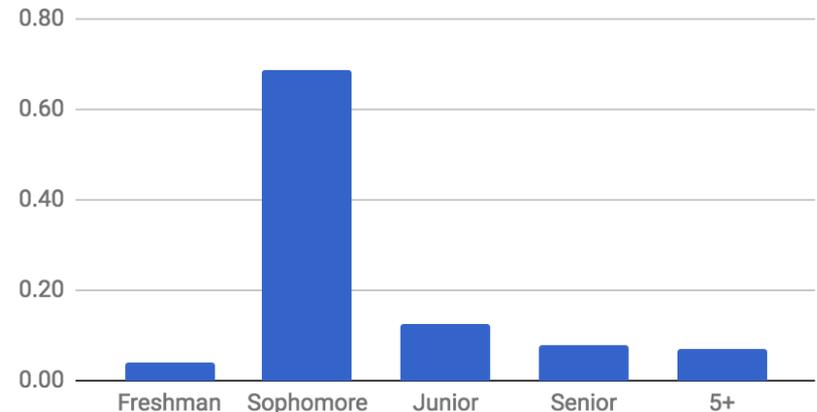
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Junior	0.08	0.02	0.02	0.02	0.13
Senior	0.02	0.05	0.01	0.01	0.08
5+	0.02	0.01	0.05	0.05	0.07
<b>Marginal Status</b>	0.65	0.23	0.13	0.11	

Marginal Lunch Probability

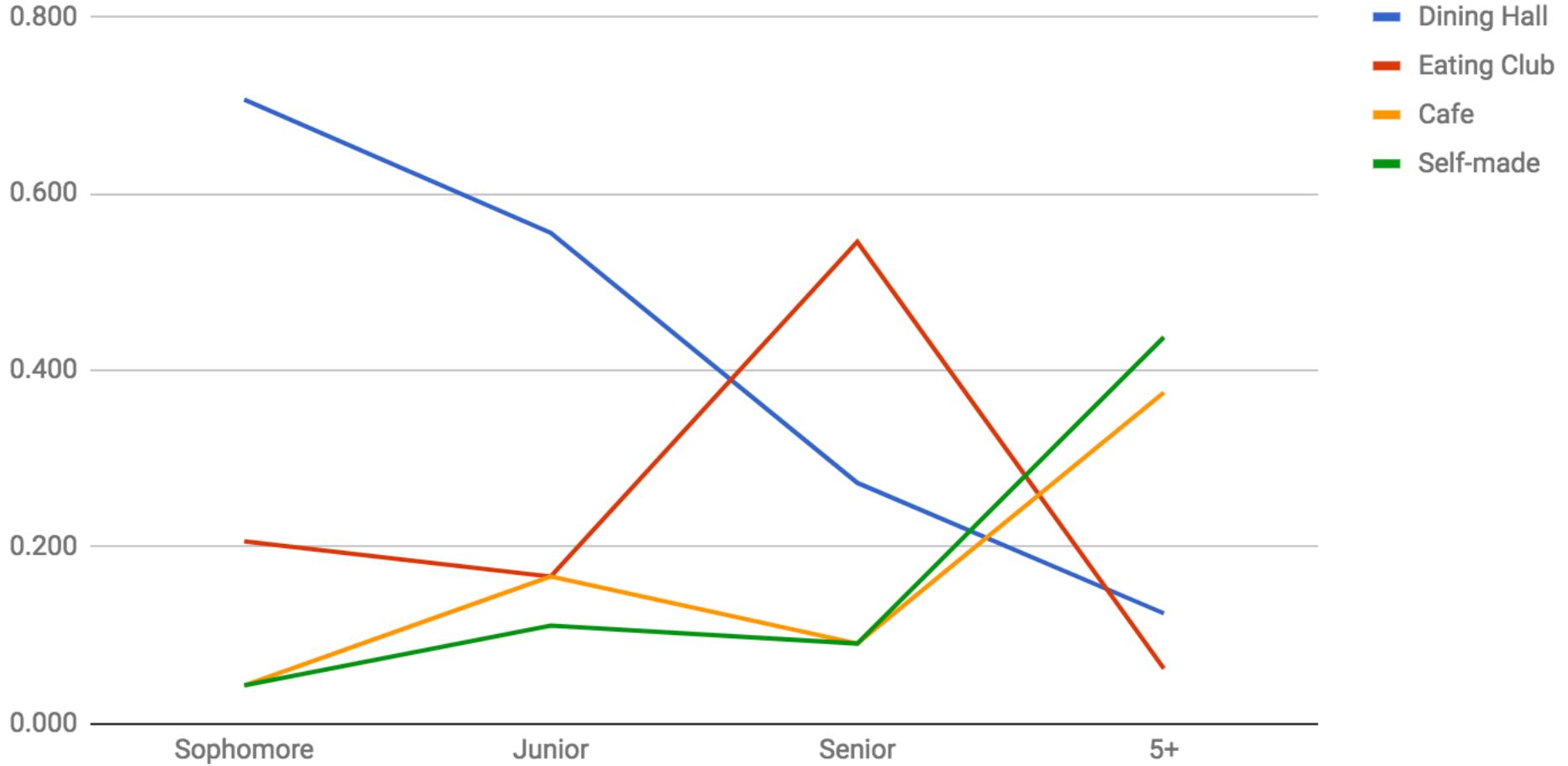


Marginal Year



# Lunch | Year

## Lunch Type | Year



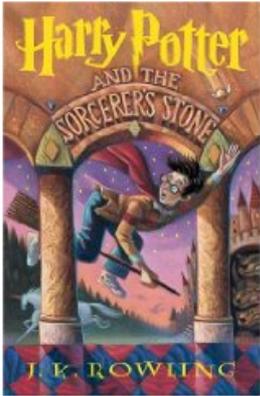
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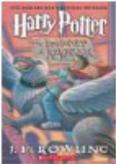
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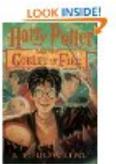
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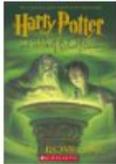
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# Continuous Conditional Distributions

Let  $X$  and  $Y$  be continuous random variables

$$P(X = x|Y = y) = \frac{P(X = x, Y = y)}{P(Y = y)}$$

$$f_{X|Y}(x|y) \cdot \epsilon_x = \frac{f_{X|Y}(x|y) \cdot \epsilon_x \cdot \epsilon_y}{f_Y(y) \cdot \epsilon_y}$$

$$f_{X|Y}(x|y) = \frac{f_{X|Y}(x|y)}{f_Y(y)}$$

# Mixing Discrete and Continuous

Let  $X$  be a continuous random variable

Let  $N$  be a discrete random variable

$$P(X = x|N = n) = \frac{P(N = n|X = x)P(X = x)}{P(N = n)}$$

$$P_{X|N}(x|n) = \frac{P_{N|X}(n|x)P_X(x)}{P_N(n)}$$

$$f_{X|N}(x|n) \cdot \epsilon_x = \frac{P_{N|X}(n|x)f_X(x) \cdot \epsilon_x}{P_N(n)}$$

$$f_{X|N}(x|n) = \frac{P_{N|X}(n|x)f_X(x)}{P_N(n)}$$

# All the Bayes Belong to Us

M,N are discrete. X, Y are continuous

OG Bayes

$$p_{M|N}(m|n) = \frac{P_{N|M}(n|m)p_M(m)}{p_N(n)}$$

Mix Bayes #1

$$f_{X|N}(x|n) = \frac{P_{N|X}(n|x)f_X(x)}{P_N(n)}$$

Mix Bayes #2

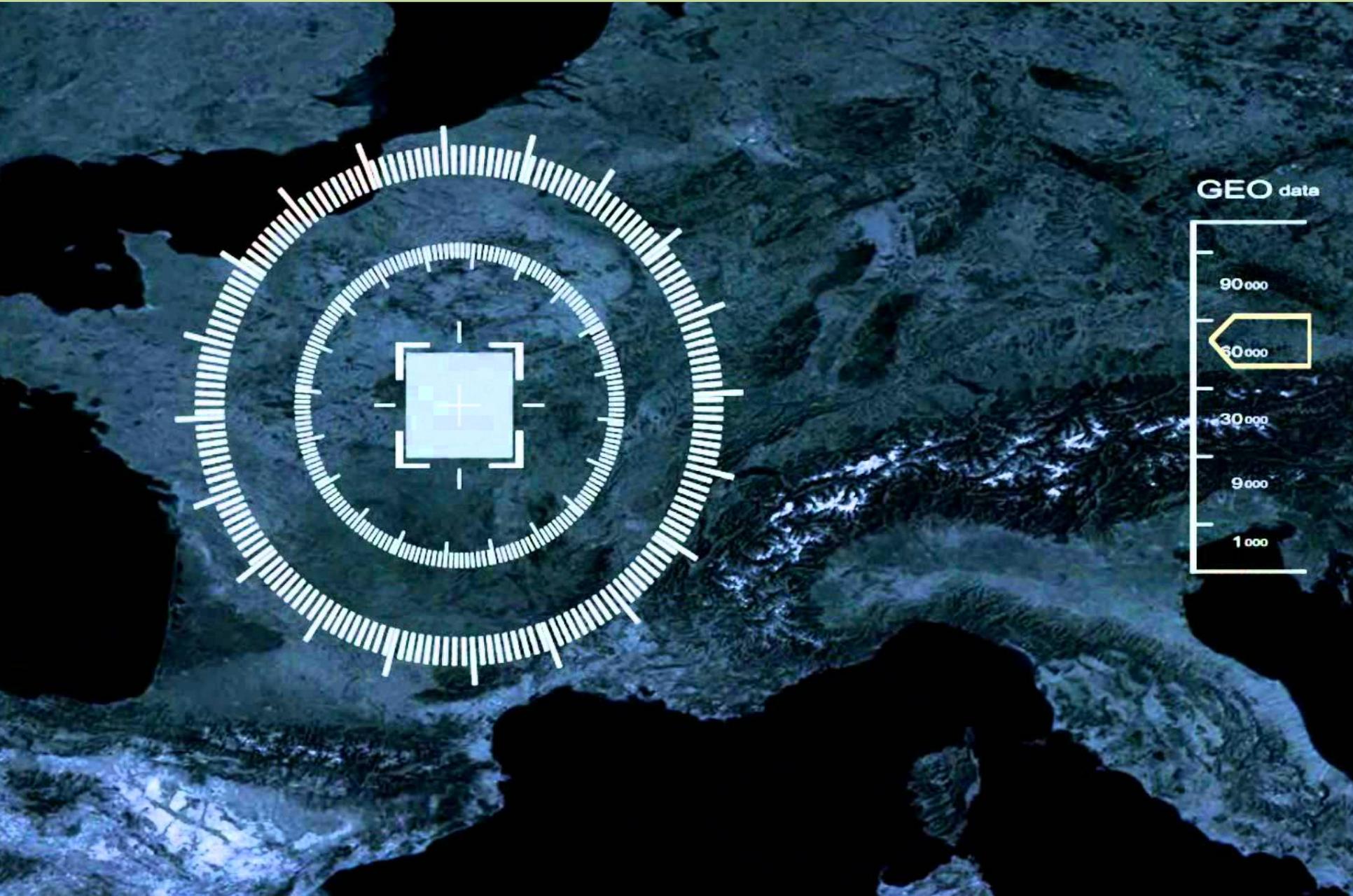
$$p_{N|X}(n|x) = \frac{f_{X|N}(x|n)p_N(n)}{f_X(x)}$$

All Continuous

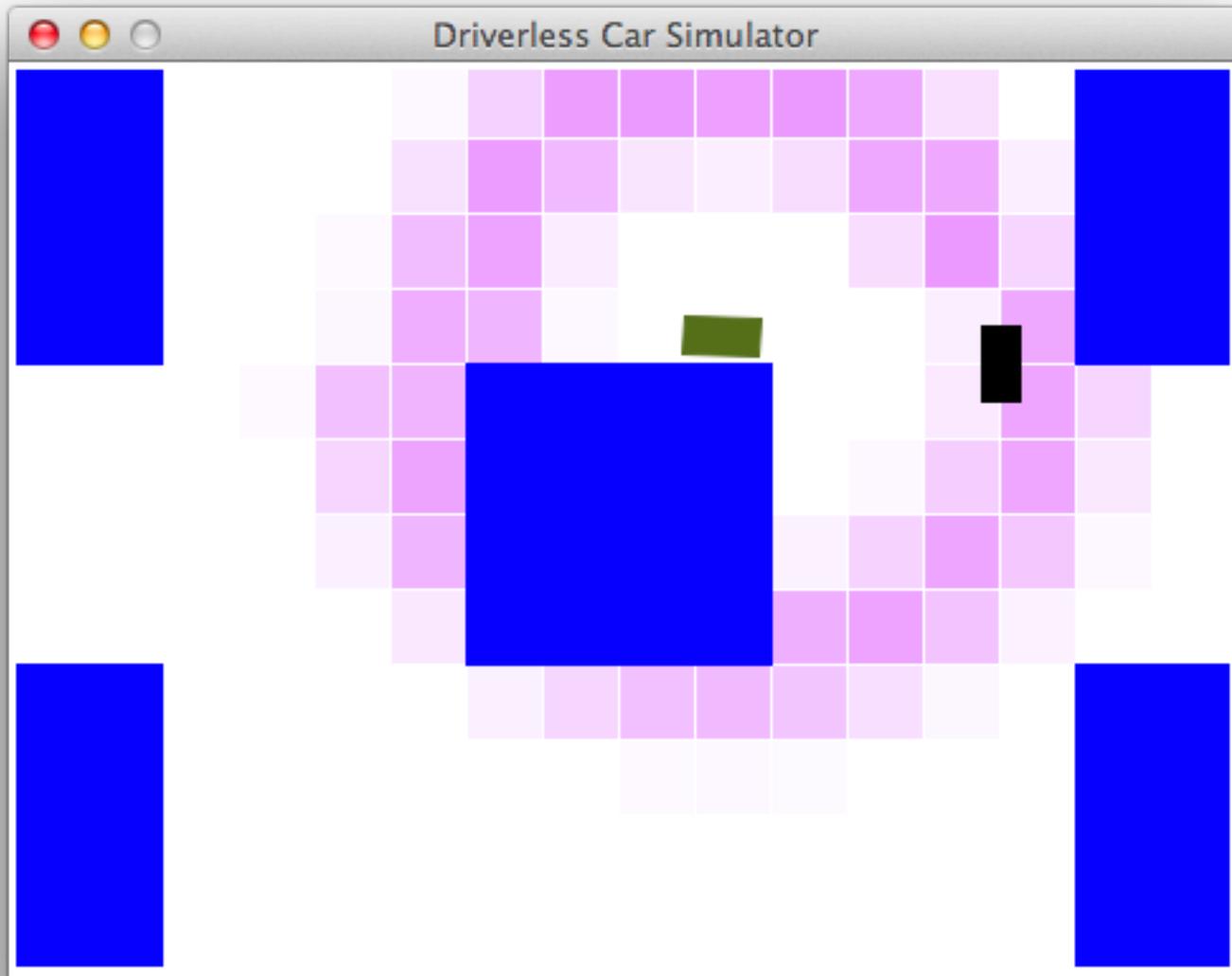
$$f_{X|Y}(x|y) = \frac{f_{Y|X}(y|x)f_X(x)}{f_Y(y)}$$



# Tracking in 2D Space?



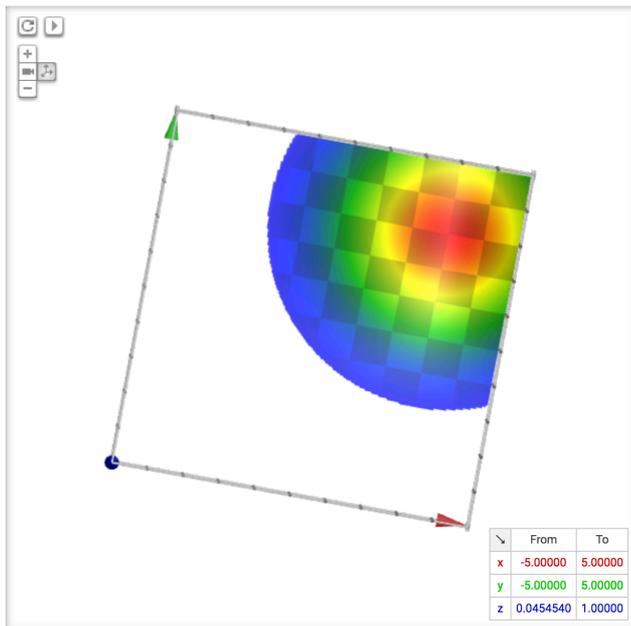
# Tracking in 2D Space: CS221



# Bivariate Normal

- $X, Y$  follow a symmetric bivariate normal distribution if it has PDF:

$$f_{X,Y}(x, y) = \frac{1}{2\pi\sigma^2} \cdot e^{-\frac{[(x-\mu_x)^2 + (y-\mu_y)^2]}{2\cdot\sigma^2}}$$



Here is an example where

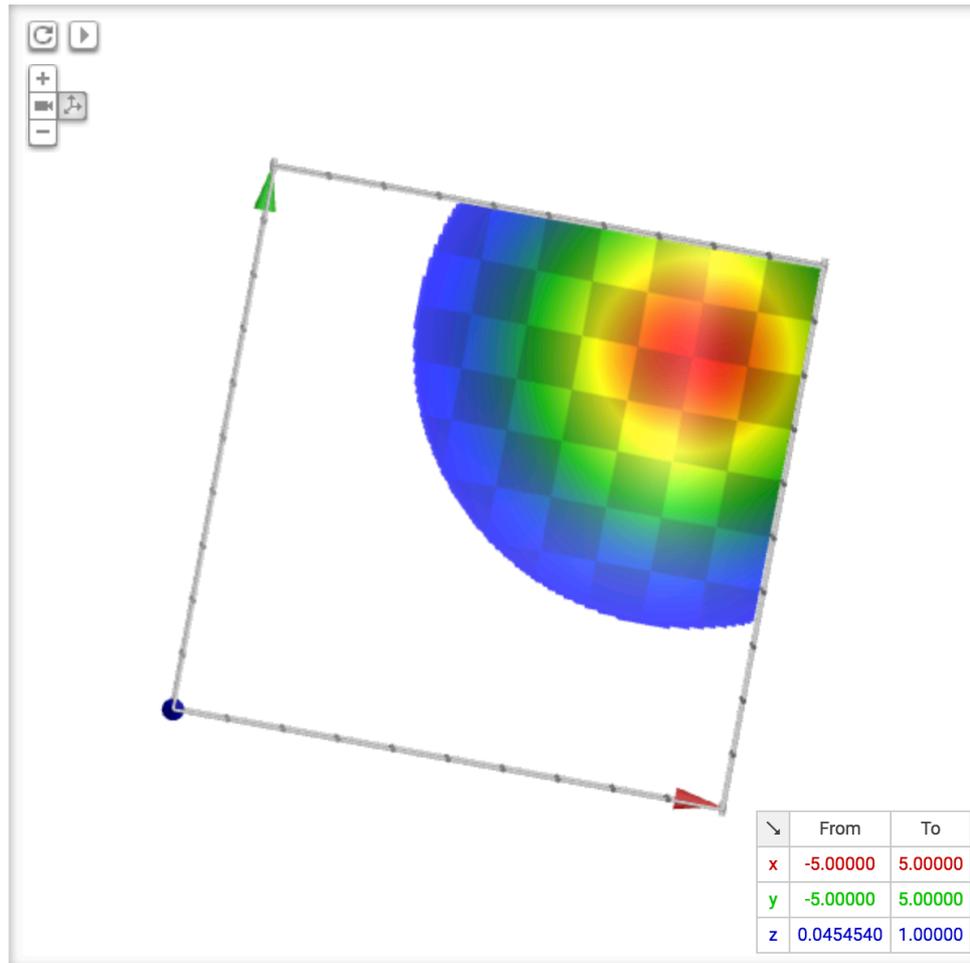
$$\mu_x = 3$$

$$\mu_y = 3$$

$$\sigma = 2$$

# Tracking in 2D Space: Prior

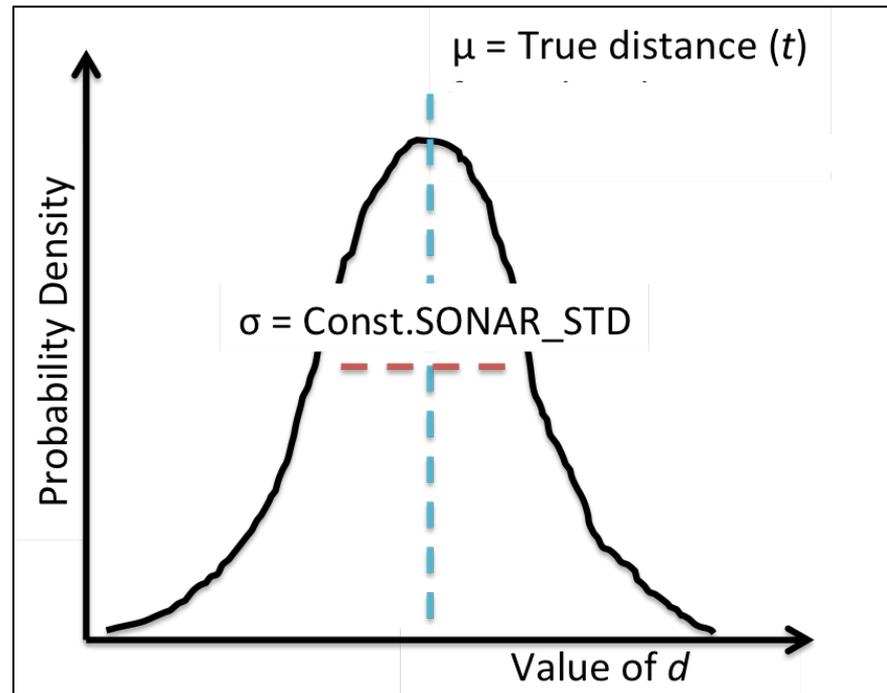
$$f_{X,Y}(x,y) = K \cdot e^{-\frac{[(x-3)^2 + (y-3)^2]}{8}}$$



# Tracking in 2D Space: Observation!

$$f_{X,Y}(x,y) = K \cdot e^{-\frac{[(x-3)^2 + (y-3)^2]}{8}}$$

$$f_{D|X,Y} \sim N(\mu = \sqrt{x^2 + y^2}, \sigma^2 = 1)$$

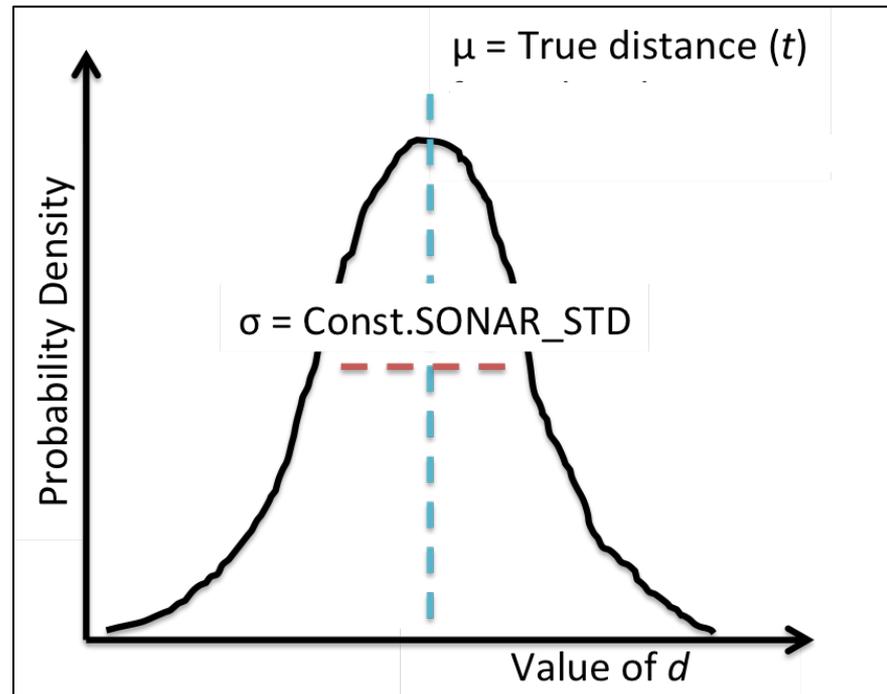


What is your new belief for the location of the object being tracked?  
Your probability density function can be expressed with a constant

# Tracking in 2D Space: Observation!

$$f_{X,Y}(x,y) = K \cdot e^{-\frac{[(x-3)^2 + (y-3)^2]}{8}}$$

$$f_{D|X,Y}(d|x,y) = K \cdot e^{-[d - \sqrt{x^2 + y^2}]^2}$$



What is your new belief for the location of the object being tracked?  
Your joint probability density function can be expressed with a constant

# Tracking in 2D Space: Posterior

$$f_{X,Y|D}(x, y|4) = K \cdot e^{-[(4 - \sqrt{x^2 + y^2})^2 + \frac{(x-3)^2 + (y-3)^2}{8}]}$$

